

Linde Hydraulics Media. Information.

Our media at a glance.

All documents can be found in the download area of our website.

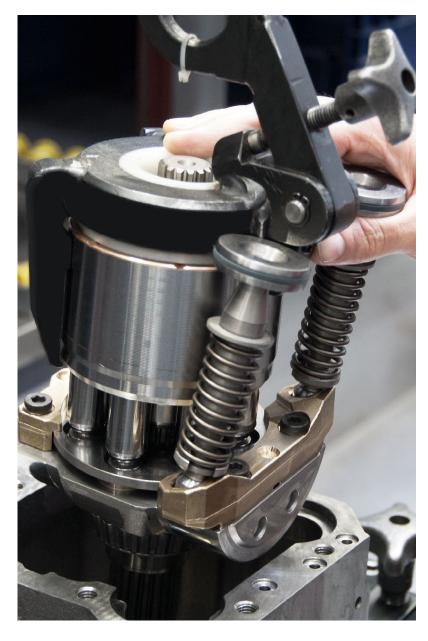
| PRODUCT CATALOGUE | DATASHEETS | BROCHURES | FACT SHEETS | CAD DOWNLOADS |
|--|--|--|--|--------------------------|
| General technical data. | General technical data. | General technical data. | General technical data. | 3D models in *.stp file. |
| Design characteristics & Product advantages. | |
| Portfolio overview. | Technical specification. | Application examples. | Application examples. | |
| | Functional descriptions. | | | |





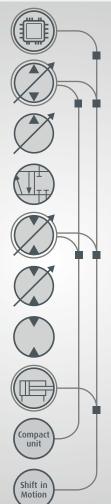
www.linde-hydraulics.com

Linde Hydraulics Product Catalogue. **Content.**



| OUR SERVICES | | Linde Hydraulics Lifecycle. | 3 |
|--------------------------------|----------------|-----------------------------|-----------------|
| ELECTRONICS | | Controllers & Diagnostics. | |
| | PUMPS | Variable displacement. | |
| | PUMPS | Self-regulating. | |
| | CONTROL VALVES | Monoblock & Modular. | |
| | MOTORS | Variable displacement. | |
| HIGH PRESSURE HYDRAULICS | | Self-regulating. | |
| | | Fixed displacement. | |
| | ACTUATORS | Shift actuator. | |
| | SYSTEMS | Pump/Motor - Compact unit. | Compact |
| | | Shift in Motion. | Shift in Motion |
| LINDE HYDRAULIC | S WORLDWIDE | Sales & Service partners. | |









Our Services. **Linde Hydraulics Lifecycle.**



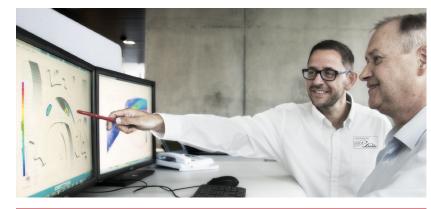


Regardless of whether you contact us in person or by other means, with us you will always find your solution as quickly as possible.

Linde Hydraulics offers you a wide range of solutions for your construction, forestry or agricultural machinery. Get an overview on our website. In the download area you will not only find layout examples for your application, but also data and fact sheets with technical details of our portfolio. In addition, 3D (step) models of our products can be used to determine the required installation space. A global network of sales partners always offers you a local contact person - together with our team of application engineers we will support and verify your layout.

→ You can find a **sales partner** close to you on our website at **www.linde-hydraulics.com/worldwide**





Development & Application Engineering

Regardless of whether you need standard or customized solutions, our engineers will develop what brings you forward – under all operating conditions.

Benefit from our expertise and the wealth of experience of our engineers in every step of the product development process:

- Common product development
- Worldwide project support
- Pulse and endurance testing beyond the application requirements
- Customized project coaching
- System training for specific applications

Our Services Linde Hydraulics Lifecycle.







Regardless of being at the prototyping and commissioning stage or series production, with systems and expert knowledge, we always ensure high quality and reliability.

We are already well prepared before we come to you to commission your machine. During the development of the iCon® controller, for example, we use the design parameters of your machine to create a simulation model, with which a majority of the functions can already be programmed and tested by computer. During commissioning on site, we can then fully concentrate on the fine adjustment of the parameters. The so-called partial integration by means of Hardware-In-The-Loop test systems significantly shortens the development period of the controls and offers you more flexibility in designing your machine functions.

Even when our products are finally ready for series production, we do not lean back or rest on the fact that we have a very competent and experienced team. With a holistic quality concept, we ensure consistently high quality and reliability completely independent of variance or quantity.





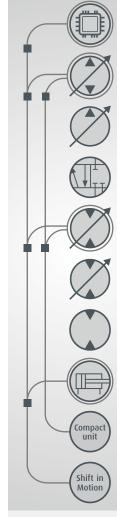
Spare parts & Remanufacturing

You matter to us! We are there for you for more than one lifetime

In case you have to hurry! With our outstanding parts availability, our global network of service partners and the accustomed Linde quality, we are there for you when you need us. It doesn't matter whether you need a single part in the event of a breakdown or whether we prepare your units for the next harvest.

- → Just visit our online-shop at https://shop.linde-hydraulics.com/ Here you can find all spare parts tailored to your needs easily via the serial number of your unit. A defined stock of parts is available within 24 hours!
- → For repair and remanufacturing services you can find a **service partner** close to you on our website at www.linde-hydraulics.com/worldwide

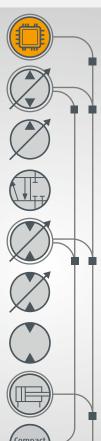


















Product advantages

- Cost-efficient configuration of manifold functions: from simple controls to complex and safety-critical systems
- Software with customer-specific adaptations
- Short development cycles
- Demand-oriented extension and simple implementation in overall vehicle network



Fields of application

| iCon 100 | iCon 200 | iCon 300 |
|----------|--------------|--------------|
| ✓ | \checkmark | \checkmark |
| ✓ | ✓ | ✓ |
| | ✓ | ✓ |
| | ✓ | ✓ |
| | | ✓ |

General technical data

| | | Controller | | | | | |
|----------|--------------|--------------|--------|--|--|--|--|
| | Safety level | Function | Safety | | | | |
| iCon 100 | PLb | \checkmark | | | | | |
| iCon 200 | PLd | \checkmark | ✓ | | | | |
| iCon 300 | PLd | \checkmark | ✓ | | | | |

| Co | nnect | tor | | | Out | puts | | | | | | Inputs | | | | Com | . Interf | faces |
|----------|-------|--------------|-------------------|------------------------------|------------|--------------------------|-------------------------------------|---------------------------|------------|-----------------------|----------------------------------|--------|----------------|--------------|----------|-----|----------|---------|
| | AMP | | Out, max. | Jt groups) | Out | current | nt controller B | r supply, 250 mA | 0-5 V | , L | ensors) | | dn | PullDown | | | | |
| 42 Pin | | 70 Pin | HighSide 0 3 A | HighSide Out (switched in | LowSide Ou | LowSide cu controller | LowSide current for side A and B | Ext. power 5 V, max. 2 | Analog In, | Frequency 0-10 kHz | Inductive sensors (frequency) | PWM In | Digital PullUp | Digital Pull | Ignition | CAN | RS232 | USB |
| √ | 1 | | 3 | n/a | 3 | 2 | n/a | 1 | 6 | 5 | 1 | n/a | 13 | n/a | 1 | 2 | n/a | n/a |
| ✓ | | | 7 | n/a | n/a | 4 | 4 | 1 | 6 | 5 | 1 | n/a | 2 | n/a | 1 | 2 | n/a | n/a |
| | | \checkmark | 8 | 1 | 2 | 8 | n/a | 2 | 12 | 4 | 1 | 2 | 6 | 4 | 1 | 3 | 1 | option. |

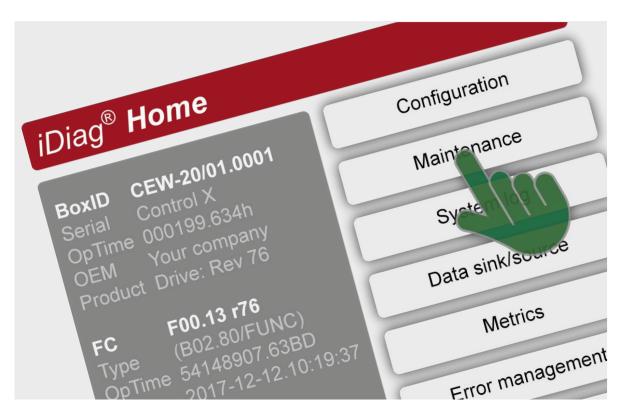
Electronics. **Diagnostics. iDiag**®.

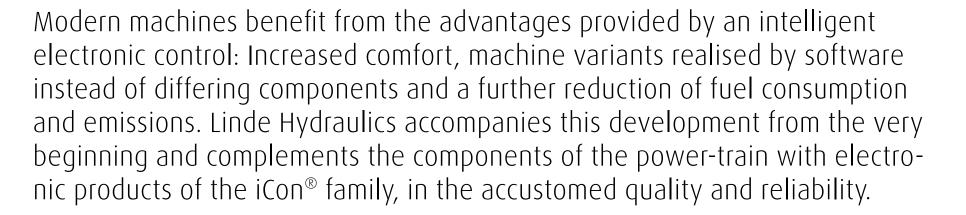
Design characteristics

- Diagnostic system compatible with iCon Controllers
- Parameterization
- "Teach in" of components
- Harness checking
- Data logger suited for PC/laptop with Windows operating system with serial or USB interface

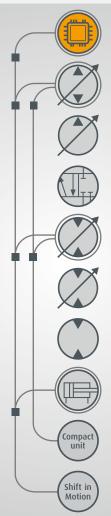
Product advantages

- Optimum system usage by teach-in function
- Efficient trouble shooting
- Easy usage by self-explanatory user surface
- Practical-minded partition of control elements by functional groups
- Modular set-up: individual functions can be added optionally later





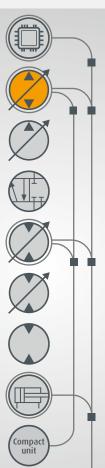


















Design characteristics

- Axial piston pump in swashplate design
- Clockwise or counter clockwise rotation
- Integrated high pressure relief valves with charge function
- Hydrostatic plain bearing of the swashplate

Product advantages

- Precise and load-independent
- High power density
- Long service life

All the controls used in the Series 02 are based on a load-independent control mechanism. No matter which control is used: identical commands always result in the same response in the machine. The sensitive and precise machine control makes work easier and increases productivity. Various customer system options for mechanical, hydraulic and electric input solutions are available. Further special regulating features like torque control and pressure cut-off are also available. The reliable control of the pump can easily be integrated into any kind of vehicle management control system.



General technical data

| HPV-02 | | | | | | |
|---|---|--------|--|--|--|--|
| Nominal size | | | | | | |
| Displacement | Max. displacement | cc/rev | | | | |
| Coood | Max. operating speed | rpm | | | | |
| Speed | Max. speed* | rpm | | | | |
| | Nominal pressure | bar | | | | |
| Pressure | Max. pressure** | bar | | | | |
| | Max. housing pressure | bar | | | | |
| Torque | Torque (Δp=430 bar; charge press.=20 bar) | Nm | | | | |
| Corner power (theor.) (Vmax x nmax x Δ p 430 bar) kW | | | | | | |
| Weight (approx.)*** (with H1-control, without oil) kg | | | | | | |

| 55 | 75 | 105 | 135 | 165 | 210 | 280 |
|------|------|------|-------|-------|-------|-------|
| 54.7 | 75.9 | 105 | 135.7 | 165.6 | 210.1 | 281.9 |
| 3900 | 3400 | 3200 | 3000 | 2750 | 2300 | 2400 |
| 4150 | 3600 | 3400 | 3200 | 2950 | 2500 | 2550 |
| 450 | 450 | 450 | 450 | 450 | 450 | 450 |
| 500 | 500 | 500 | 500 | 500 | 500 | 500 |
| 2.5 | 2.5 | 2.5 | 2.5 | 2.5 | 2.5 | 2.5 |
| 374 | 519 | 719 | 929 | 1133 | 1438 | 1929 |
| 153 | 185 | 241 | 292 | 326 | 346 | 485 |
| 46 | 49 | 66 | 72 | 113 | 132 | 164 |

Customer interfaces

| Control options**** | | | | | | | | |
|--------------------------------|--------------|------------|------------------|-----------------|----------------|--|-------------|--|
| | Proportional | 3-Position | Pressure cut-off | Enable function | Torque Control | | Swash andle | |
| Electro-hydraulic Hydraulic | ✓ ✓ | ✓ ✓ | ✓ ✓ | ✓ ✓ | ✓ ✓ | | ✓ | |
| Mechanic | \checkmark | | | ✓ | | | | |

| Flanges | | | | | | | |
|---------|--------------|--|--|---|--------|--|--|
| | 2 hole | 2 hole, 4 additional threads M12 | 2 hole, 4 additional threads M16 | 2 hole, additional holes (d=17,5mm) | 4 hole | | |
| SAE-B | | | | | | | |
| SAE-C | \checkmark | \checkmark | | | | | |
| SAE-D | \checkmark | | \checkmark | \checkmark | | | |
| SAE-E | | | | | ✓ | | |

ensors

| Shafts**** | | | | | | |
|---|---------------------------------------|----------|--|--|--|--|
| ISO 3019-1 (SAEJ 744) ANSI B92.1-1970 | Compagnion flange SAE J 1946 Typ A | DIN 5480 | | | | |
| ✓ | ✓ | ✓ | | | | |

| PT0 | P | Ports | | | | | | |
|----------------|----------------|------------------------------------|------------|--|--|--|--|--|
| Power take-off | | ISO 6162-2 Radial twin ports | 150 6149-1 | | | | | |
| , | Work ports | ✓ | | | | | | |
| √ | Threaded ports | | ✓ | | | | | |

^{*} highest transient speed, that can temporarily occur | ** highest transient pressure, that can temporarily occur | *** highest transient speed, that can temporarily occur | *** highest transient speed, that can temporarily occur | *** highest transient speed, that can temporarily occur | *** highest transient speed, that can temporarily occur | *** highest transient speed, that can temporarily occur | *** highest transient speed, that can temporarily occur | *** highest transient speed, that can temporarily occur | *** highest transient speed, that can temporarily occur | *** highest transient speed, that can temporarily occur | *** highest transient speed, that can temporarily occur | *** highest transient speed, that can temporarily occur | *** highest transient speed, that can temporarily occur | *** highest transient speed, that can temporarily occur | *** highest transient speed, that can temporarily occur | *** highest transient speed, that can temporarily occur | *** highest transient speed, that can temporarily occur | *** highest transient speed, that can temporarily occur | *** highest transient speed, that can temporarily occur | *** highest transient speed, that can temporarily occur | *** highest transient speed, that can temporarily occur | *** highest transient speed, that can temporarily occur | *** highest transient speed, that can temporarily occur | *** highest transient speed, that can temporarily occur | *** highest transient speed, that can temporarily occur | *** highest transient speed, that can temporarily occur | *** highest transient speed, that can temporarily occur | *** highest transient speed, that can temporarily occur | *** highest transient speed, that can temporarily occur | *** highest transient speed, that can temporarily occur | *** highest transient speed, that can temporarily occur | *** highest transient speed, that can temporarily occur | *** highest transient speed, that can temporarily occur | *** highest transient speed, that can temporarily occur | *** highest tran

Open Circuit.

Self-Regulating Pump. HPR-02.



Legal emission regulations force manufacturers of mobile machinery to optimize the noise emission of their products. Since secondary measures tend to be expensive and less efficient Linde Hydraulics prefers to fight the noise where it is generated: by optimally connecting an additional volume directly next to the commutation of the HPR-02 pump, Linde Hydraulics invented the SPU silencer. The adaptive SPU reduces pressure pulsations in the regulating pump over the entire range of operation – without loss of power.

Design characteristics

- Axial piston pump in swashplate design
- Exact controllers with and without position feedback
- Adaptive noise optimization SPU
- Hydrostatic plain bearing of the swashplate

Product advantages

- Excellent suction up to rated speed
- High power density
- Energy saving operation by 'flow on demand'-control

General technical data

| HPR-02 | | | |
|-----------------------------------|--|--------|--|
| Nominal size | | | |
| Displacement | Max. displacement | cc/rev | |
| Speed | Max. operating speed (without tank pressurization) | rpm | |
| Volume flow | Max. volume flow* | I/min | |
| | Nominal pressure | bar | |
| Pressure | Max. pressure** | bar | |
| | Max. housing pressure | bar | |
| Torque | Torque | Nm | |
| Corner power (theoretical) kW | | | |
| Weight (approx.) (without oil) kg | | | |

| 55 | 75 | 95 | 105 | 135 | 165 | 210 | 280 |
|-------|-------|-------|-------|-------|-------|-------|-------|
| 55 | 75.9 | 94.7 | 105 | 135.7 | 163.6 | 210.1 | 281.9 |
| 2700 | 2500 | 2500 | 2500 | 2350 | 2400 | 2100 | 2000 |
| 148.5 | 189.8 | 237.5 | 246.8 | 312.1 | 392.6 | 441.2 | 563.8 |
| 420 | 420 | 350 | 420 | 420 | 350 | 420 | 420 |
| 500 | 500 | 420 | 500 | 500 | 420 | 500 | 500 |
| 2.5 | 2.5 | 2.5 | 2.5 | 2.5 | 2.5 | 2.5 | 2.5 |
| 368 | 507 | 528 | 702 | 907 | 911 | 1404 | 1884 |
| 104 | 132.8 | 138 | 172.7 | 218.5 | 229 | 308.8 | 394.7 |
| 39 | 39 | 44.5 | 50 | 65 | 74 | 116 | 165 |

| | uen | erar technical data |
|-------|-------|---------------------|
| | | |
| 105 D | 125 D | 165 D |
| 210 | 2x125 | 2x165 |
| 2450 | 2400 | 2100 |
| 514.5 | 600.0 | 695.5 |
| 420 | 350 | 420 |
| 500 | 420 | 500 |
| 2.5 | 2.5 | 2.5 |
| 1245 | 1393 | 1964 |
| 319.4 | 337 | 431.8 |
| 96 | 113 | 177 |
| | | |

| | | Contro | ol options**** | | | |
|----------------------|------------------|------------------------------|-------------------------------|---|-----------------------------|--|
| | pressure cut-off | hydraulic ApLS – override | electrical ApLS – override | electric stroke limiter and pressure cut-off | hyperbolic power limiter | hyperbolic power limiter and pressure cut-off |
| | | | | | | |
| | | | | | | |
| Load sensing | \checkmark | \checkmark | \checkmark | \checkmark | \checkmark | |
| Electro-proportional | | | | | | \checkmark |

| Sen | sors |
|-------------|--------------|
| Swash angle | Speed sensor |
| ✓ | |

| | Shafts**** | |
|---|---|----------|
| ISO 3019-1 (SAEJ 744) ANSI B92.1- 1970 | Compagnion flange SAE J 1946 Typ A | DIN 5480 |
| ✓ | ✓ | ✓ |





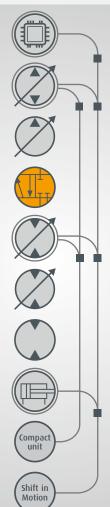


















Open Circuit. Monoblock Control Valves.

Design characteristics

- Basic block: three directional control valves of identical nominal size in one cast housing
- Designed for the Linde Synchron Control (LSC) -
- Load Sensing System
- Nominal sizes 30, 25 and 18
- Flows up to 600 l/min (size 30)
- Broad dimensioned diameters and flow-optimized design of the supply channels
- Extendable with directional control valves in sandwich design, in identical or differing nominal size
- Pressure cut-off and additional functions integrated in connection plate
- Special functions via intermediate plates
- Optionally with hydraulic or electric piloting

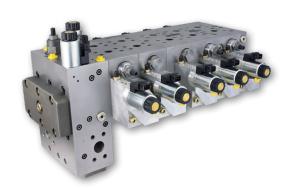
Product advantages

- All advantages of the LSC valve technology
- Compact design
- Full-size expandability
- High efficiency achieved by flow-optimized channels even for applications with numerous actuators

Three directional control valves in a common housing form the base of the manifold valve plate in monoblock design. This results in the most compact package.

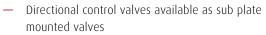
With its latest LSC generation, Linde Hydraulics combines the design characteristics of the proven LSC system with the benefits of the electric control. The powerful electronic control unit recognises the operator's command by the amplitude and the speed with which the joysticks are being moved. It then sets the pump and the valves according to the dynamic demand. Due to the overlaid, classic load-sensing control mechanism, no sensors are needed.

All components are provided by a single source and matched perfectly with each other. The operator can change the system's behaviour electronically with regard to its dynamics and fine control, as well as its dependency or independency on the load. This enables multi-purpose machines which can quickly be optimized to the specific use by the operator. With completely opened valves, the actuators can be controlled exclusively via the pump's control to achieve the maximum possible efficiency.



Open Circuit. **Modular Control Valves.**





- Designed for the Linde Synchron Control (LSC) Load Sensing System
- Nominal sizes 25 and 30
- Flows up to 600 l/min (size30)
- Modular design for the configuration of valve plates for 1-8 actuators
- Optionally with hydraulic, electric or combined piloting



- All advantages of the LSC valve technology
- Easy to configure building block system
- Adjustable to the target application
- Quick availability
- Ideal for machines with low production volume

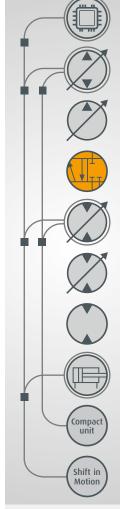


Manifold valve plates of series VT modular are made up of individual components of a modular building block system. This is why manifold valve plates can be configured to optimally match any application with one up to eight actuators.

The directional control valves are at the core of every manifold plate in LSC technology. Compared to other load sensing directional control valves, LSC directional control valves stand apart, in particular, thanks to the integrated downstream pressure compensators and pressure copiers. — This arrangement prevents the actuator from lowering when the function starts.

As a result of the compact design, the oil flow only needs to pass through the valve once and not several times. This ensures optimized flow passages in the directional control valve. Due to the high-precision production of the directional control valves, there is only minimal leakage even at high load, which is beneficial to the load holding function of the valves.

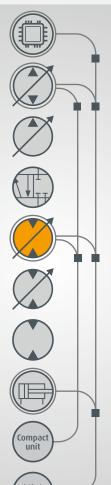
















Open & Closed Circuit. Variable Displacement Motor. CMV.

Design characteristics

- Axial piston motor in bent axis design
- Standardized interfaces
- Speed sensor optional

Product advantages

- High speeds
- High power density
- Low windage losses

With the next generation of the bent axis motors, Linde Hydraulics expands its customer oriented portfolio of high-quality components for hydraulic systems. Due to their standardized interfaces, e.g. the plug-in flange according to ISO, the CMV and CMF fit a high variety of applications, without the need of adaptors. The motors enable a more cost effective operation of the respective applications thanks to low windage losses and lighter weight.



SIZE AT DEVELOPMENT STAGE. CONTACT US!

General technical data

| CMV | | |
|--------------|--|--------|
| Nominal size | | |
| Displacement | Max. displacement | cc/rev |
| | Max. operating speed at V _{max} | rpm |
| Speed | Max. speed at V _{max} * | rpm |
| | Max. operating speed at V _{min} | rpm |
| | Max. speed at V _{min} * | rpm |
| | Nominal pressure | bar |
| Pressure | Max. pressure** | bar |
| | Max. housing pressure | bar |
| Torque | Output torque (Δ p=430 bar and Vmax) | Nm |
| Corner power | (Vmax x nmax at Vmin x ∆p 430 bar) | kW |
| Weight | approx. (without oil) | kg |

| | | × | | | | |
|------------|------|-------|-------|------|------|--|
| 60 | 85 | 115 | 140 | 170 | 215 | |
| 60 | 85 | 115 | 140 | 170 | 215 | |
| 4450 | 3900 | 3550 | 3250 | 3100 | 2900 | |
| on request | | | | | | |
| 7200 | 6800 | 6150 | 5600 | 4900 | 4600 | |
| | | on re | quest | | | |
| 450 | 450 | 450 | 450 | 450 | 450 | |
| 500 | 500 | 500 | 500 | 500 | 500 | |
| 2.5 | 2.5 | 2.5 | 2.5 | 2.5 | 2.5 | |
| 411 | 582 | 787 | 958 | 1163 | 1471 | |
| 191 | 238 | 293 | 336 | 378 | 447 | |
| 27.7 | 36.3 | 44.8 | 59.2 | 62.1 | 76.4 | |

| Control options | | | | | | |
|-------------------|--------------|--------------|--------------------------------------|--------------------------------------|-------------------|--|
| | Proportional | 2-Position | default = Vmin (positive control) | default = Vmax (negative control) | Pressure override | |
| Electro-hydraulic | \checkmark | \checkmark | \checkmark | \checkmark | \checkmark | |
| Hydraulic | \checkmark | \checkmark | \checkmark | \checkmark | \checkmark | |

| Sens | sors | | Flanges | | | | |
|-------|------|------------|------------|--------------------------|-------------------------|--|--|
| Speed | | 150 3019-1 | (SAEJ 744) | ISO 3019 – 2 (metric) | Plug-in ISO 3019 – 2 | | |
| ✓ | | , | / | ✓ | ✓ | | |
| | | | | | | | |

| | Shafts**** | |
|---|---------------------------------------|----------|
| ISO 3019-1 (SAEJ 744) ANSI B92.1-1970 | Compagnion flange SAE J 1946 Typ A | DIN 5480 |
| ✓ | ✓ | ✓ |

| Ports | | | | | | |
|--------------------------|---------------------------------|--------------|--|--|--|--|
| ISO 6162-2 Side ports | ISO 6162-2 Twin ports (rear) | 150 6149 – 1 | | | | |
| \checkmark | \checkmark | | | | | |
| | | \checkmark | | | | |
| | | | | | | |

^{*} highest transient speed, that can temporarily occur | ** highest transient pressure, that can temporarily occur | **** Availability depends on nominal size

Open & Closed Circuit.

Variable Displacement Motor. HMV-02.



Standard hydraulic motors at low speeds in their starting phase cannot generate the necessary torque. Therefore, the power of the fast spinning hydraulic motors has to be reduced by means of several step gearboxes down to the speed needed on the wheel. Somewhat higher windage losses and poorer mechanical efficiency are benevolently accepted in this context. Quite the opposite holds true for the motors by Linde Hydraulics: The motors of the Series 02 are capable of transmitting the required torque even at low speed and make it possible to start smoothly and sensitively.

Design characteristics

- Axial piston motor in swashplate design
- Optimized starting and low speed behaviour
- Swivelling to 0 cc/rev
- Hydrostatic plain bearing of the swashplate

Product advantages

General technical data

- PTO through-drive motor
- Jerk-free low speed
- Large conversion range
- Extremely high angular acceleration possible

| | | | | | | - | | | | | |
|--------------|--|--------|------|------|------|----------|-------|------|-------|-------|--|
| HMV-02 | | | | | | | | | | | |
| Nominal size | | | 55 | 75 | 105 | 135 | 165 | 210 | 280 | 105 D | |
| Displacement | Max. displacement | cc/rev | 54.7 | 75.9 | 105 | 135.6 | 165.6 | 210 | 281.9 | 210 | |
| | Max. operating speed at V_{max} | rpm | 4300 | 3800 | 3700 | 3200 | 3100 | 2700 | 2400 | 3300 | |
| Spood | Max. speed at V _{max} * | rpm | 4400 | 4100 | 3800 | 3500 | 3400 | 3000 | 2700 | 3400 | |
| Speed | Max. operating speed at V_{min} | rpm | 4700 | 4400 | 4100 | 3700 | 3500 | 3200 | 2900 | 4100 | |
| | Max. speed at V _{min} * | rpm | 5300 | 5000 | 4700 | 4000 | 3900 | 3500 | 3200 | 4400 | |
| | Nominal pressure | bar | 450 | 450 | 450 | 450 | 450 | 450 | 450 | 450 | |
| Pressure | Max. pressure** | bar | 500 | 500 | 500 | 500 | 500 | 500 | 500 | 500 | |
| | Max. housing pressure | bar | 2.5 | 2.5 | 2.5 | 2.5 | 2.5 | 2.5 | 2.5 | 2.5 | |
| Torque | Output torque (Δ p=430 bar and Vmax) | Nm | 374 | 519 | 719 | 928 | 1133 | 1438 | 1929 | 1437 | |
| Corner power | (Vmax x nmax at Vmin x △p 430 bar) | kW | 184 | 239 | 309 | 360 | 415 | 482 | 586 | 677 | |
| Weight | approx. (without oil) | kg | 28 | 32 | 42 | 56 | 76 | 101 | 146 | 98 | |

| | delielai tetiilitai data |
|-------|--------------------------|
| | |
| 105 D | 165 D |
| 210 | 331.2 |
| 3300 | 2900 |
| 3400 | 3100 |
| 4100 | 3500 |
| 4400 | 3700 |
| 450 | 450 |
| 500 | 500 |
| 2.5 | 2.5 |
| 1437 | 2267 |
| 677 | 878 |
| 98 | 149 |

| Control options | | | | | | |
|-------------------|--------------|--------------|---------------|---------------|-------------------|-------------------------|
| | Proportional | 2-Position | default= Vmin | default= Vmax | Pressure override | Pressure side selection |
| Electro-hydraulic | \checkmark | \checkmark | \checkmark | \checkmark | \checkmark | \checkmark |
| Hydraulic | \checkmark | \checkmark | | \checkmark | \checkmark | |

| Sen | sors | |
|--------------|------|--|
| | | |
| | | |
| | | |
| | | |
| Speed | | |
| S | | |
| \checkmark | | |
| | | |

| Flanges | | | | | |
|---------|--------------|----------|--|--|--|
| | | | | | |
| | | | | | |
| | υ U | Φ | | | |
| | 2 hole | 4 hole | | | |
| SAE C | ✓ | | | | |
| SAE D | \checkmark | | | | |
| SAE E | | √ | | | |

| : | Shafts**** | |
|---|---------------------------------------|----------|
| ISO 3019-1 (SAEJ 744) ANSI 892.1-1970 | Compagnion flange SAE J 1946 Typ A | DIN 5480 |
| ✓ | ✓ | ✓ |

| Through drive | |
|--|--|
| Only for nominal sizes 105, 135, 165, 210, 280, 1050, 165D | |
| ✓ | |

| Port | ts | | |
|----------------|----------------------|---------------------|--------------|
| | ISO 6162-2 Radial | ISO 6162-2 Axial | 150 6149 – 1 |
| Work ports | \checkmark | \checkmark | |
| Threaded ports | | | √ |
| | | | |



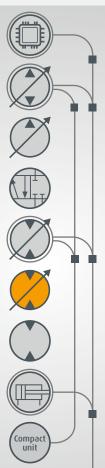


















Design characteristics

- Axial piston motor in swashplate design
- High pressure relief valves available
- Brake pressure shut off for closed circuit
- Hydrostatic plain bearing of the swashplate

Product advantages

- High power density
- Dynamic response
- High reliability

In conventional drives the torque of the hydraulic motor can be transmitted to the cardan shaft only by means of a dropbox. For further optimization of the drive train Linde Hydraulics developed the Through-Drive Motor. Based on the standard hydraulic motor of the Series 02 with just one shaft end, the Through-Drive Motor offers two shaft ends to transmit the torque. Hence the machine designer can conceive the hydraulic motor to fit directly and immediately into the drive train thus saving mounting space. The dropbox usually needed in a conventional propulsion drive can be omitted. This reduces both noise emission and fabrication cost of the entire vehicle while overall efficiency increases.



General technical data

| HMR-02 | | |
|--------------|--|--------|
| Nominal size | | |
| Displacement | Max. displacement | cc/rev |
| | Max. operating speed at V_{max} | rpm |
| Coood | Max. speed at V _{max} * | rpm |
| Speed | Max. operating speed at V_{min} | rpm |
| | Max. speed at V _{min} * | rpm |
| | Nominal pressure | bar |
| Pressure | Max. pressure** | bar |
| | Max. housing pressure | bar |
| Torque | Output torque (Δ p=430 bar and Vmax) | Nm |
| Corner power | (Vmax x nmax at Vmin x △p 430 bar) | kW |
| Weight | approx. (without oil) | kg |

| 55 | 75 | 105 | 135 | 165 | 210 | 280 |
|------|------|------|-------|-------|-------|-------|
| 54.7 | 75.9 | 105 | 135.6 | 165.6 | 210.1 | 281.9 |
| 4300 | 3800 | 3700 | 3200 | 3100 | 2700 | 2400 |
| 4400 | 4100 | 3800 | 3500 | 3400 | 3000 | 2700 |
| 4700 | 4400 | 4100 | 3700 | 3500 | 3200 | 2900 |
| 5300 | 5000 | 4700 | 4000 | 3900 | 3500 | 3200 |
| 450 | 450 | 450 | 450 | 450 | 450 | 450 |
| 500 | 500 | 500 | 500 | 500 | 500 | 500 |
| 2.5 | 2.5 | 2.5 | 2.5 | 2.5 | 2.5 | 2.5 |
| 374 | 519 | 719 | 928 | 1133 | 1438 | 1929 |
| 184 | 239 | 309 | 360 | 415 | 482 | 586 |
| 28 | 32 | 42 | 56 | 76 | 101 | 146 |

| | Contro | l optic | ns | | | |
|-------------------|--------------|--------------|---------------|---------------|-------------------|-------------------------|
| | Proportional | 2-Position | default= Vmin | default= Vmax | Pressure override | Pressure side selection |
| Electro-hydraulic | | \checkmark | \checkmark | | \checkmark | \checkmark |
| Hydraulic | | \checkmark | \checkmark | | \checkmark | |

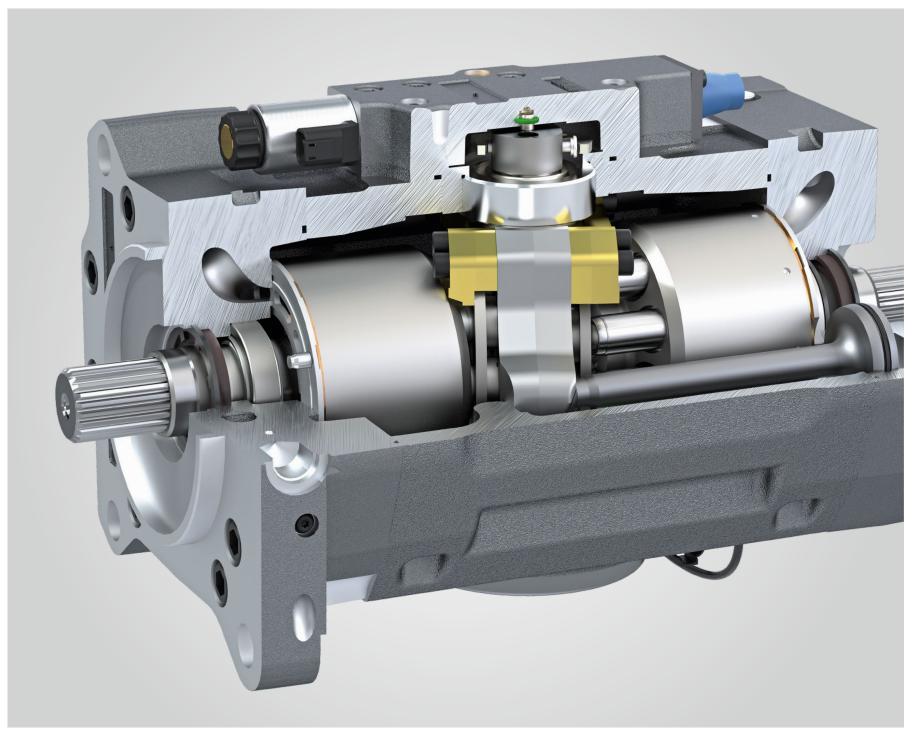
| Sensors | | Flanges | |
|---------|-------|--------------|--------------|
| Speed | | 2 hole | 4 hole |
| Sp | SAE C | \checkmark | |
| / | SAE D | \checkmark | |
| V | SAE E | | \checkmark |
| | | | |

| Shafts**** | |
|---------------------------------------|----------|
| Compagnion flange SAE J 1946 Typ A | DIN 5480 |
| ✓ | ✓ |
| | |

| Through drive | |
|---|--|
| Only for nominal sizes 135, 165, 210 | |
| ✓ | |

| Po | rts*** | | |
|----------------|----------------------|---------------------|--------------|
| | ISO 6162-2 Radial | ISO 6162-2 Axial | ISO 6149 – 1 |
| Work ports | \checkmark | \checkmark | |
| Threaded ports | | | \checkmark |

^{*} highest transient speed, that can temporarily occur | ** highest transient pressure, that can temporarily occur | **** Availability depends on nominal size



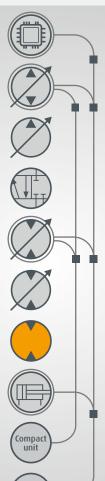


















Design characteristics

- Fixed displacement bent axis motor
- Standardized interfaces
- Plug-in flange available

Product advantages

- High power density
- High speeds
- Very small dimensions

With the next generation of the bent axis motors, Linde Hydraulics expands its customer oriented portfolio of high-quality components for hydraulic systems. The fixed displacement motor CMF is characterized by its high external load and speed capacity. Due to its standardized interfaces, e.g. the plug-in flange according to ISO, the CMF fits a high variety of applications, without the need of adaptors. Low windage losses in combination with the low weight of the motor support the cost-effective operation of the application.



General technical data

| CMF | | |
|-------------------|------------------------------------|------------------|
| Nominal size | | |
| Displacement | | cc/rev |
| Speed | Max. operating speed | rpm |
| эреец | Max. speed* | rpm |
| | Nominal pressure | bar |
| Pressure | Max. pressure** | bar |
| | Max. housing pressure | bar |
| Torque | (∆p=430 bar; charge press.=20 bar) | Nm |
| Corner power (the | POΓ.) (Vmax X Nmax X Δρ 430 bar) | kW |
| Weight (approx.)* | ** (without oil) | kg |
| 3 () , | | , and the second |

| 80 |
|------|
| 80 |
| 4500 |
| 5000 |
| 450 |
| 500 |
| 2.5 |
| 547 |
| 258 |
| 23.0 |

| Sensors | | Flanges | |
|---------|---|--------------------------------------|--|
| Speed | ISO 3019-1 / SAE J'44, SAE C 4-bolt: 127-4 | ISO 3019-2 metric, 140 mm, 4-bolt | Plug-in, similar to 150 3019-2, 190 mm, 2-bolt |
| ✓ | ✓ | ✓ | ✓ |

| | Shafts**** | |
|---|---------------------------------------|----------|
| ISO 3019-1 (SAEJ 744) ANSI 892.1-1970 | Compagnion flange SAE J 1946 Typ A | DIN 5480 |
| ✓ | ✓ | ✓ |

| | | Ports**** | |
|----------------|---------------------------------|--------------------------|--------------|
| | ISO 6162-2 Radial twin ports | ISO 6162-2 Side ports | 150 6149 – 1 |
| Work ports | \checkmark | \checkmark | |
| Threaded ports | | | \checkmark |

^{*} highest transient speed, that can temporarily occur | ** highest transient pressure, that can temporarily occur | **** Availability depends on nominal size

Open & Closed Circuit.

Fixed Displacement Motor. HMF-02/HMA-02.

Design characteristics

- Fixed displacement swashplate motor
- High pressure relief valves set fixed or variable opt.
- Robust and simple design
- Hydrostatic plain bearing of the swashplate

Product advantages

General technical data

- High power density

| _ | Steady | low speed | |
|---|--------|-----------|--|
| | | | |

| _ | Reliable | and | easv | to | maintain |
|---|----------|-----|------|----|----------|
| | | | | | |

| HMF-02/HMA-02 | 2 | | | | |
|--------------------------------------|------------------------------------|--------|--|--|--|
| Nominal size | | | | | |
| Displacement | | cc/rev | | | |
| C | Max. operating speed | rpm | | | |
| Speed | Max. speed* | rpm | | | |
| | Nominal pressure | bar | | | |
| Pressure | Max. pressure** | bar | | | |
| | Max. housing pressure | bar | | | |
| Torque | (Δp=430 bar; charge press.=20 bar) | Nm | | | |
| Corner power (th | eof.) (Vmax X Nmax X Δρ 430 bar) | kW | | | |
| Weight (approx.)*** (without oil) kg | | | | | |

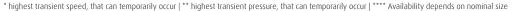
| 28 | 35 | 55 | 63 | 75 | 85 | 105 | 135 | 165 | 210 | 280 |
|------|------|------|------|------|------|------|-------|-------|------|-------|
| 28.6 | 35.6 | 54.7 | 63 | 75.9 | 85.6 | 105 | 135.6 | 165.6 | 210 | 281.9 |
| 4500 | 4500 | 4100 | 3900 | 3800 | 3600 | 3500 | 3200 | 3100 | 2700 | 2400 |
| 4800 | 4800 | 4400 | 4200 | 4100 | 3850 | 3800 | 3500 | 3400 | 3000 | 2700 |
| 450 | 450 | 450 | 450 | 450 | 450 | 450 | 450 | 450 | 450 | 450 |
| 500 | 500 | 500 | 500 | 500 | 500 | 500 | 500 | 500 | 500 | 500 |
| 2.5 | 2.5 | 2.5 | 2.5 | 2.5 | 2.5 | 2.5 | 2.5 | 2.5 | 2.5 | 2.5 |
| 196 | 244 | 374 | 431 | 519 | 586 | 719 | 928 | 1133 | 1438 | 1929 |
| 92 | 115 | 161 | 176 | 207 | 221 | 263 | 311 | 368 | 407 | 485 |
| 16 | 16 | 19 | 24 | 26 | 33 | 33 | 39 | 76 | 101 | 146 |

| Sens | ors | Flanges | | |
|-------|-----|---------|--------------|--------------|
| | | | | |
| | | | | |
| | | | 2 hole | 4 hole |
| P | | SAE B | ./ | 7 |
| Speed | | SAE D | V | |
| 5 | | SAE C | \checkmark | |
| / | | SAE D | \checkmark | |
| V | | SAE E | | \checkmark |

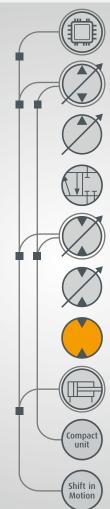
| | Shafts**** | |
|---|--------------------------------------|----------|
| ISO 3019-1 (SAEJ 744) ANSI B92.1-1970 | Compagnion flange SAEJ 1946 Typ A | DIN 5480 |
| \checkmark | ✓ | ✓ |

| Through drive |
|------------------------------------|
| Only for nominal sizes 210, 280 |
| ✓ |

| | Ports**** | |
|----------------|----------------------|--------------|
| | | |
| | | |
| | | - |
| | ISO 6162-2 Radial | 150 6149 - |
| | ISO 6 Radii | 150 6 |
| Work ports | \checkmark | |
| Threaded ports | | \checkmark |



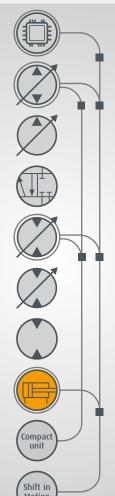
















Closed Circuit. **Shift Actuator. Actuator.**

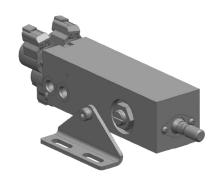
Design characteristics

- Electro-hydraulic multi-position cylinder (3 positions)
- Prepared for mounting of clevis or spherical head
- Simple and robust design

Product advantages

- Defined and exact switching operations
- Easy implementation in conventional gearboxes
- Small space requirement and high reliability

The use of hydraulic cylinders for shifting gears requires not only fast and precise shifting processes, but also defined and electronically sensable rest positions as well as a defined behavior in case of system failure. The actuator from Linde Hydraulics combines all these properties and accommodates them in a robust and compact housing. Together with the shift rod, which is prepared to accommodate conventional connections, all requirements for easy implementation are met. More information can be found in the "Shift in Motion" section.



General technical data

| Actuator | | |
|-----------|-----------------|-----|
| | | |
| Force | Shifting force | N |
| roice | Detent force | N |
| Stroke | Shifting stroke | mm |
| Pressure | Supply pressure | bar |
| riessuie | Tank pressure | bar |
| Positions | | |

| 1000 +/- 300 |
|---|
| 450 +/- 100 |
| ±9.5 |
| 25±5 (Typically, this is charge pressure of the drive system) |
| <2 |
| 3 (1-N-2) |
| |

| Control options | | | | |
|-------------------|--------------|--------------|---------------|-------------------|
| | 12 V | 24 V | AMP Connector | Deutsch Connector |
| Electro-hydraulic | \checkmark | \checkmark | | \checkmark |

| illiead of the | e siiiit iou | |
|----------------|--------------|------|
| | M 16 | |
| | | |
| Netric thread | \checkmark | Thre |

| POILS | |
|----------------|--------------------------|
| | ISO 6149-1, M14 x 1.5 |
| Threaded ports | \checkmark |
| | |

| Sensors |
|------------------------------|
| |
| |
| 5 |
| Proportional position sensor |
| sition |
| P P C |
| ✓ |

Closed Circuit.

Pump/Motor - Compact Unit. K-02.



Together with the customer Linde Hydraulics defines new standards in technology. Advanced modular drive technology, realised in hydrostatic variators for variable speed transmission, form the core of power split gearboxes.

Compact units with a hollow shafts are available for mounting to conventional gearboxes in smaller machines. These compact units are used as fully hydrostatic systems with additional mechanical PTO drive. In this way, a further function can be operated independently of the travel function.

With customer-specific developments, Linde Hydraulics supports the change from power shift to continuous variable transmission technology.

Design characteristics

- HPV-02 and HMF-02 back-to-back in common unit
- Version for powersplit transmission and direct drive solutions (e.g. orchard tractors)
- Integrated high pressure relief valves with charge and purge function

Product advantages

General technical data

- Precise crawling speed
- Compact design
- Low fuel consumption over entire operating range
- Mechanical throughdrive (in addition to travel drive)

| K-02 | | |
|---|----------------------|--------|
| Nominal size | | |
| Displacement | Max. displacement | cc/rev |
| Coood | Max. operating speed | rpm |
| Speed | Max. speed* | rpm |
| | Nominal pressure | bar |
| Pressure | Max. pressure** | bar |
| Max. housing pressure | | bar |
| Torque (Δp=430 bar; charge press.=20 bar) N | | Nm |
| Corner power (theor.) (Vmax x nmax x Δ p 430 bar) kV | | |

| 75/75 | 105/105 |
|-------|--|
| 75/75 | 105/105 |
| 3400 | 3200 |
| 3600 | 3400 |
| 450 | 450 |
| 500 | 500 |
| 2.5 | 2.5 |
| 519 | 719 |
| 185 | 241 |
| | 75/75 75/75 3400 3600 450 500 2.5 519 |

| Control option | | | | | |
|-------------------|--------------|------------|------------------|-----------------|--|
| | Proportional | 3-Position | Pressure cut-off | Enable function | |
| Electro-hydraulic | ✓ | | | ✓ | |
| | | | | | |

| Sensors | | | |
|-------------|--------------|--|--|
| Swash angle | Speed sensor | | |
| ✓ | ✓ | | |

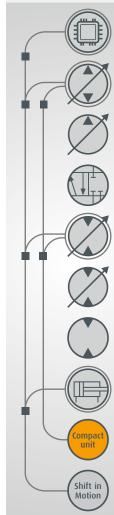
| Flanges | | | | | |
|---------|--------------|--|--|---|--------|
| | 2 hole | 2 hole, 4 additional threads M12 | 2 hole, 4 additional threads M16 | 2 hole, additional holes (d=17,5mm) | 4 hole |
| SAE-B | | | | | |
| SAE-C | \checkmark | | | | |
| SAE-D | | | | | |
| SAE-E | | | | | |

| Shafts**** | | | |
|---|--|--|--|
| ISO 3019-1 (SAEJ 744) ANSI B92.1-1970 | Compagnion flange SAE J 1946 Typ A | | |
| ✓ | ✓ | | |

| | Ports | | |
|----------------|--------------------------|--------------------------|------------|
| | ISO 6162-2 Side ports | ISO 6162-2 Twin ports | 150 6149-1 |
| Work ports | | | |
| Threaded ports | | | ✓ |



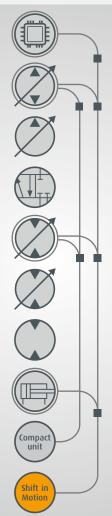
















Closed Circuit. **Hydrostatic Drive. Shift in Motion.**

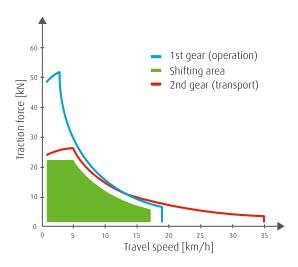
Design characteristics

- Hydrostatically controlled synchronization of stop to shift gearboxes
- Full utilization of the kinetic energy while changing the gears
- The system includes only two additional components compared to conventional drives

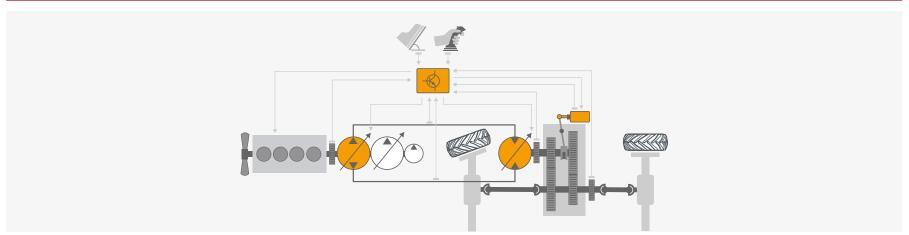
Product advantages

- Autom. and jerkless gear changes (<0.7 sec.) without standstill and the need of expensive synchromesh gear boxes
- Considerable reduction of fuel consumption and noise emission
- Minimum space requirement

Shift in Motion enables shifting procedures in a moving machine, equipped with a manual transmission that is intended to be shifted at standstill by electro-hydraulically synchronising the drivetrain. This system is particularly suitable for vehicles that often change between transport and operation, i.e. vehicles that require both high tractive effort and a high top speed above 25 kilometres per hour. The shifting procedure is load-free thanks to electrohydraulically synchronised gears and the ability to adjust the drive component's speed and torque. This makes the shifting procedures wear-free and also increases the transmission's efficiency.



Concept



Implementation

| | Linde Hydraulics components | | |
|--|-----------------------------|----------|--|
| | Electronic control unit | iCon | |
| | Variable displacement pump | HPV-02 | |
| | Variable displacement motor | HMV-02 | |
| | Shift actuator | Actuator | |





Closed Circuit.

Hydrostatic Drive. Shift in Motion.

Application examples



45 kW 70 kW 250 kW 35 kW 90 kW 250 kW

| | Equipment | | Equipment |
|---|-----------------------|---|-----------------------|
| Α | 1 x HPV 75-02 E2 | Α | 1 x HPV 105-02 E2 |
| В | 1 x HMV 105-02 E6 | В | 1 x HMV 135-02 E6 |
| C | 1 x iCon [®] | C | 1 x iCon [®] |
| D | 1 x Actuator | D | 1 x Actuator |

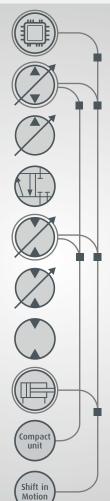
















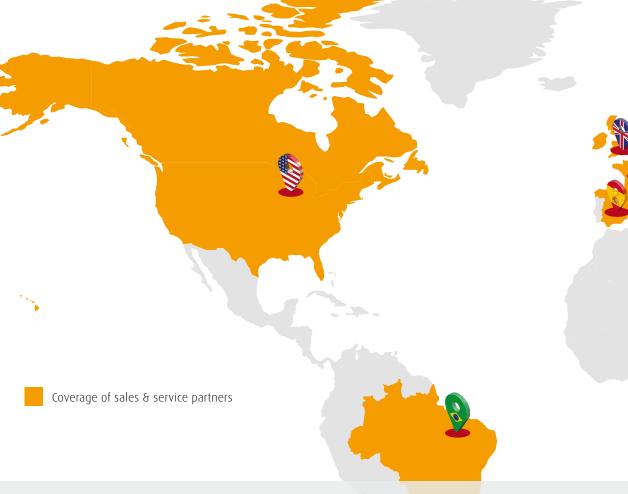


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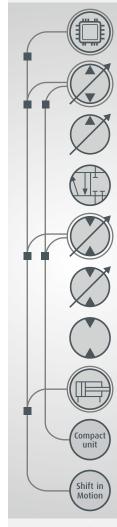


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HY.PC.02/20.

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